

Network dynamics reconstruction from data

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Abstract: We consider the problem of recovering the model of a complex network of interacting dynamical units from time series of observations. We focus on typical networks which exhibit heterogeneous degrees, i.e. where the number of connections varies widely across the network, and the coupling strength for a single interaction is small. In these networks, the behavior of each unit varies according to their connectivity. Under these mild assumptions, our method provides an effective network reconstruction of the network dynamics. The method is robust to a certain size of noise and only requires relatively short time series on the state variable of most nodes to determine: how well-connected a particular node is, the distribution of the nodes' degrees in the network, and the underlying dynamics.

Key words: Dynamical systems, complex networks

1. Introduction

Many severe disorders such as Parkinson's disease, schizophrenia, and dyslexia are believed to be associated with anomalous brain connectivity [1]. The key role that connectivity plays in a network function is not restricted to neuroscience. Indeed, examples are found in engineering [2, 3], physics [4, 5], and biology [6–8]. To understand and control such systems, as well as to predict sudden changes of behavior, one often needs a faithful description of the governing rules and connectivity structure of the networks involved.

Reconstructing the connectivity structure of a network from data is a daunting task due to the high dimensionality of the network dynamics. Often there is no lack of data for the observed dynamics at each node, and the main challenge is to understand how to use this data to understand how the dynamics is influenced by the thousands or millions of interactions among the elements of the network [9, 10].

Recently, the problem of reconstructing the network connectivity from multivariate data has attracted a great deal of attention [11–16]. Advanced methods can tackle the case of a few coupled phase oscillators [17–23]. For networks of moderate size, approaches based on information measures can be used under the assumption that the interaction strength is large enough to induce nonlinear collective dynamics [24–26]. However, in large networks the interaction strength per connection is typically weak and the multitude of interactions are organized in an intricate maze composed of communities having highly connected nodes coexisting with poorly connected ones [27]. In such situations, the weak interaction allied with the chaotic dynamics of the nodes leads to an observed dynamics that, at first sight, looks like a noise signal, thereby offering a great challenge to reconstruction methods.

In this article, we provide a method to recover the statistical properties of the connectivity when the connection strength per link is weak. Our approach works when the network structure exhibits disparate

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connectivity scales such as scale-free (SF) degree distribution and when the isolated dynamics of the nodes is chaotic. With relatively short time series, our method can recover the degree distribution, build a model for the isolated dynamics and the coupling function. We also illustrate the power of this method against a certain size of additive noise from a single multivariate time series.

2. Model: network dynamics

We consider a network of N nodes with nonidentical nonlinear isolated dynamics and pairwise interaction. Such network can be described by its adjacency matrix A , whose entry A_{ij} equals 1 if nodes i and j are connected and 0 otherwise. The time evolution of the dynamics on the network is determined by

$$\mathbf{x}_i(t+1) = \mathbf{f}_i(\mathbf{x}_i(t)) + \alpha \sum_{j=1}^N A_{ij} \mathbf{h}(\mathbf{x}_i(t), \mathbf{x}_j(t)). \quad (1)$$

When performing reconstruction from data, however, the isolated local dynamics $\mathbf{f}_i: M \rightarrow M$, the coupling function \mathbf{h} , the coupling parameter α , the adjacency matrix A and even the dimension of the space M are unknown. This class of equations describe the dynamics of many important complex systems found in neuroscience [28], engineering [2, 3], superconductors [5], and biology [8] among others.

Our two basic assumptions are (i) local dynamics is close to some unknown ergodic and chaotic map \mathbf{f} , i.e. $\|\mathbf{f} - \mathbf{f}_i\| \leq \delta$ (this is usual in applications [29, 30]) and (ii) the connectivity of the network is heterogeneous. This means that the number of interactions ‘received’ by a node i (given by its in-degree $k_i = \sum_j A_{ij}$), varies widely across the network. More precisely, k_i is very small compared to N for most i , but for a relatively small number of nodes, called hubs, k_i is much larger (e.g. a SF network). Our method tests whether these two basic assumptions (i) and (ii) hold and from then on performs the reconstruction of the model.

We assume that we have access to a time series of observations $y_i(t) = \phi(\mathbf{x}_i(t))$ at each node, where ϕ is a projection to a state variable. This is often the case in applications. For instance, in neurons we have access to a membrane potential and in electronic circuits to the voltages. From this single variable, we will reconstruct the model.

3. Functional networks

Suppose that a multivariate time series is given for some fixed, but unknown, network and dynamical parameters Figures 1a and 1b. A fundamental question is whether one can recover the interaction structure from these measurements. The relation between time series and network structure is not unique, but it is believed that the important statistical information about the network connectivity is manifested in the time series [31–33].

To access the network connectivity, it is common to introduce a functional network. This consists in assigning a numerical value to the similarity between the time series of any two nodes and then construct a network according to the values obtained. There are many ways to assign a similarity value to two time series. For examples one can use correlations, mutual information, and various extensions of these [34, 35]. Let us focus on the correlation measure.

3.1. Pairwise correlations between nodes

As a measure of similarity, we use Pearson correlation between the time series $y_i(t)$ and $y_j(t)$, $t = 0, \dots, T$ (using the lexicon ordering). The similarity s_{ij} gives a measure of how similar is the effect of the coupling felt

by the nodes i and j . Then, the intensity $S_i = \sum_j s_{ij}$ approximates how many nodes have similar behavior to the node i . The paradigm is that studying the statistical properties of quantities such as the distribution of intensities we gain some insight into the network connectivity structure. Let us put this paradigm to the test by performing simulations on SF networks of chaotic systems.

3.2. Scale-free networks of coupled chaotic systems

We generate a power law graph of $N = 10^4$ nodes, using the model of networks with given expected degrees [36] with local and fully chaotic dynamics given by the logistic map $f(x) = 4x(1-x)$, coupling function h akin to diffusion $h(x, y) = \sin 2\pi y - \sin 2\pi x$. We simulate the network for a time $T = 2000$ to obtain the time series. We then compute the intensity S_i for every node and compare its distribution with the degree distribution of the network (see Fig 1(c)). The true structural exponent for the power law is $\gamma = 2.53$, on the other hand, the structural exponent estimated through the functional network is $\gamma_{\text{est}} = 3.1$ yielding nearly 25% imprecision.

The functional network therefore overestimates γ . This has drastic consequences on the predicted character of the network. Indeed, the number of connections of a hub is heavily concentrated at $k_{\text{max}} = k_{\text{min}} N^{1/(\gamma-1)}$. So, the relative inaccuracy in the maximal degree is $N^{1/\gamma-1/\gamma_{\text{est}}}$, which, in this case, leads to roughly 500% inaccuracy. This, in turn, has drastic consequences on the ability to predict emergence of collective behavior for the network dynamics [10, 37].

Aside from inaccurate γ estimation, another striking observation in Figures 1a and 1c is the absence of many points at the lowest level of $P(S)$. Abundance of low-degree nodes and rareness of high-degree nodes are common property of SF networks. The degree of such high-degree nodes are usually unique in the SF networks, therefore there are many points at the lowest level of the degree distribution. However, the correlation-based analysis is not sensitive enough to distinguish these high-degree nodes from each other. This causes the missing points on $P(S)$ and a large deviation from the degree distribution. For these reasons, we propose a new technique to extract the structural exponent by exploring the approximate ergodic behavior of the overall network dynamics.

4. Effective networks

Our method consists in building an effective network model to describe the observations. The effective network provides a model for the local dynamics, the coupling function and the statistical properties of the network, more precisely, it recovers the degree distribution. Thus, we can build a network having statistically the same characteristics as the network that generated the data, which, along with the recovered model for the local dynamics and coupling function. Our method consists of three main steps:

Step 1 : Reduced dynamics. For the sake of clarity, we describe the procedure when the reduced dynamics is a 1-dimensional map. Eq. 1 can be reduced in the following form

$$x_i(t+1) = f_i(x(t)) - \alpha k_i v(x(t)) + \alpha \xi_i(t). \quad (2)$$

where k_i is the degree of node i and ξ_i is finite size fluctuations due to reduction at node i , $v(x) = \int h(y, x) dm(y)$ and m is the Lebesgue measure. For a precise statement and details of the general setting see [10, 38].

Given the multivariate time series $\{y_1(t), \dots, y_N(t)\}$, we consider each time series separately and then perform a Takens reconstruction of the attractor for each time series $y_i(t)$. The reduction guarantees with high

probability that the dynamics is low dimensional. If the time series is high dimensional, we discard it, and otherwise, once we are in the appropriate dimension, we estimate the evolution function $g_i(x) = f_i(x) - \alpha k_i v(x)$ and we continue to the next step.

Step 2: Isolated dynamics and effective coupling function. Once we have estimated g_i for each time series, we notice that for the low-degree nodes, $\alpha k_i v$ is negligible and the dynamics at the low-degree nodes are close to f . We identify these nodes by analysing the distribution of S_i . We use the top N_{top} nodes of the highest intensity to obtain a proxy for the isolated dynamics. We then average these rules to get $\langle g \rangle \approx f$. The choice of N_{top} is not fixed and depends on the number of nodes and the fluctuation $\sigma_g^2 = \langle (g_i - \langle g \rangle)^2 \rangle$. A good heuristic to choose N_{top} is $\sigma_g^2 / N_{\text{top}}^{1/2} \ll 1$, as we have used here.

The effective coupling function. Since $\alpha k_i v = g_i - \langle g \rangle$, analyzing the family $\{g_i - \langle g \rangle\}_{i=1}^N$ can yield the shape of v up to a multiplicative constant via a nonlinear regression by imposing that $g_i - \langle g \rangle$ and $g_j - \langle g \rangle$ are linearly dependent. The choice of the base function for the fitting is supervised and depends on the particular application.

Step 3. Network Structural Statistics. After selecting a v that satisfactorily approximates $g_i - \langle g \rangle$ up to a multiplicative constant over all indices i , we estimate the parameter $\beta_i = \alpha k_i$ using a dynamic Bayesian inference. Because the fluctuations $\xi_i(t)$ are close to Gaussian we use a Gaussian likelihood function and a Gaussian prior for the distribution of the values of β_i , and hence obtain equations for the mean and variance. We split the data into epochs of 200 points and update the mean and variance iteratively.

4.1. Application: logistic maps on scale-free networks

To compare our method and the functional network approach, we test the same system as in the functional network approach (Figures 1a–1c). Consider $M = [0, 1]$, $\mathbf{x} = x$ and $\mathbf{f}_i(\mathbf{x}) = f_i(x)$ where

$$f(x) := 4x(1 - x). \quad (3)$$

It is known that for such parameter, the map f has an absolutely continuous invariant probability measure. As a coupling function, we consider

$$h(x_j, x_i) = \sin(2\pi x_j) - \sin(2\pi x_i) \quad (4)$$

and the reduction (Eq. 2) is given by $x_i(t+1) = f(x_i(t)) - \alpha k_i v(x_i(t))$, where v is defined as above. Again, we consider the reduced model $g_i(x) = f(x) - \beta_i v(x)$ in terms of the free parameter $\beta_i = \alpha k_i$. Analyzing the distribution of β_i we access the distribution of the degrees. The estimate for γ obtained applying our method is 2.55, which has an error of just 1% (Fig. 1 (d)).

To illustrate the power of our approach, we generate SF networks with distinct values of γ , and perform our reconstruction approach to get estimates for the exponent γ . The method estimates the structural exponent with a 2% accuracy (Figure 2).

5. Robustness of the reconstruction under noise

Adding some small independent noise to the dynamics does not influence much the reconstruction procedure for the logistic map. This is a consequence of stochastic stability of the local dynamics together with the persistence of the reduction [10]. On the other hand, when the fluctuations become too large the reconstruction

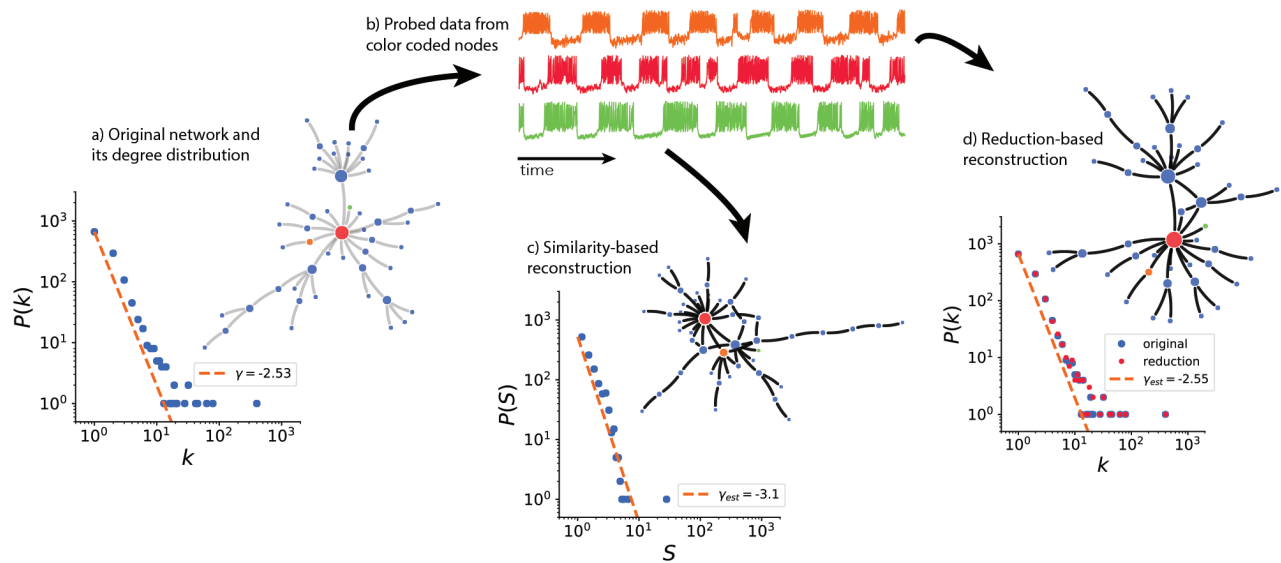


Figure 1. Reconstruction of Networks Dynamics. Measuring the state of each node in time we access the performance of the network. From time series of such measurements the goal is to reconstruct the network. Under the assumption that connections are manifested by correlations a functional network is created by measuring this quantity. Correlation analysis provides an over identification of the structural exponent. a) the original network and its degree distribution, b) the probed time series from original network, c) similarity-based reconstructed degree distribution and associated network, d) reduction-based reconstructed degree distribution and network.

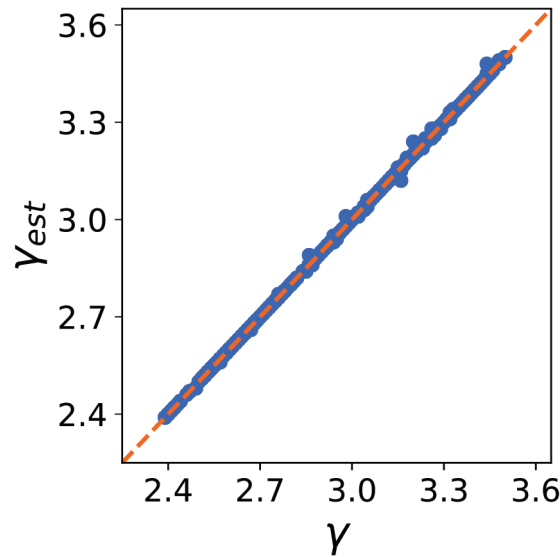


Figure 2. Reconstruction of the network statistical properties for the logistic map with diffusive coupling. The degree distribution of the network follows a power law $P(k) \propto k^{-\gamma}$. The power law exponent γ vs the estimated one γ_{est} from data.

will underestimate the network structure. To illustrate these effects, we consider the randomly perturbed various maps

$$x_i(t + 1) = f_i(x(t)) + \eta_i(t),$$

where the random variables $\eta_i(t)$ are independent over i and t , and identically distributed uniformly in the interval $[-\eta_0, \eta_0]$. Intuitively, as long as $\eta_0 < \alpha \min k_i$ the reconstruction will go through as the noise fluctuation will not compete with the coupling term. Notice that we normalize $\|v\| = 1$.

Now, we illustrate the robustness against noise with three dynamical systems logistic map, Bernoulli map and Henón map. For all the applications the network structure selected as follows the system size of the network $N = 10^5$ and $\min k_i = 1$.

5.1. Application: logistic map

The effect of noise on coupled logistic maps for $\alpha \min k_i = 0.0013$ is illustrated in Figure 3. In inset a) the noise has a smaller support $\eta_0 = 0.001$ than the critical noise level, and the reconstruction performs accurately. In inset b) the noise has a large support $\eta_0 = 0.003$, the reconstruction underestimate the number of low degree nodes.

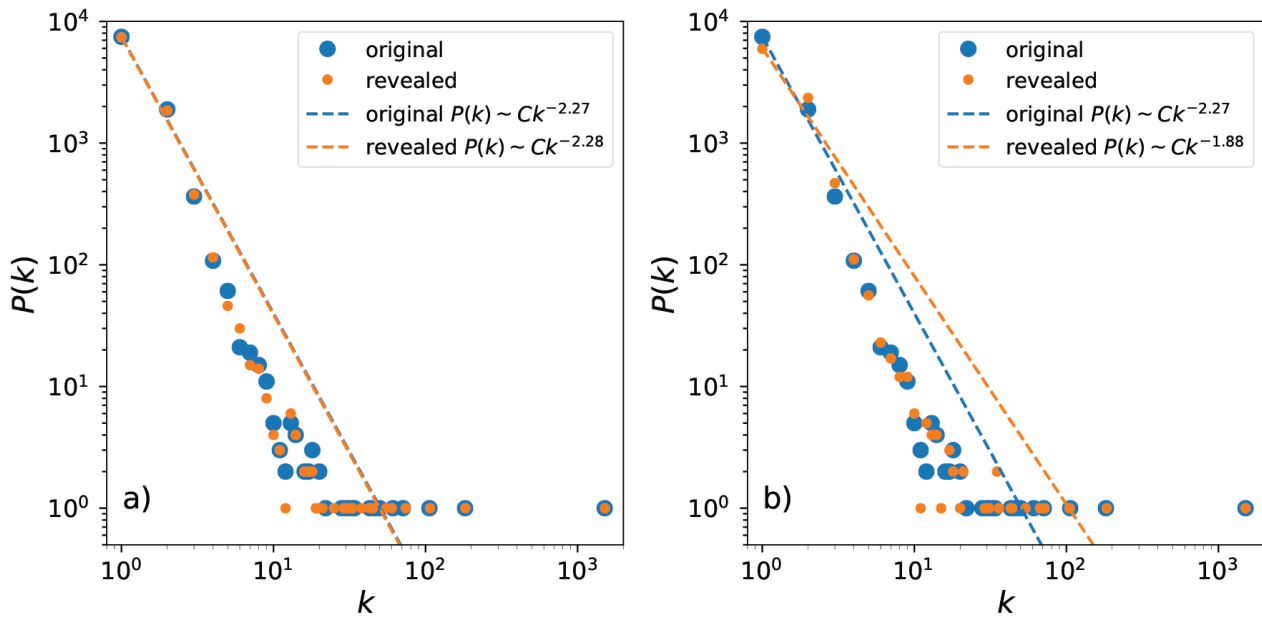


Figure 3. Performance of the reconstruction for coupled logistic maps under effect of noise. When stochastic perturbations are moderate, the effective networks provide sharp estimates on the network structure. If the noise is large, the difference between the time series at low and high degree nodes becomes blurred. Inset a) shows that the reconstruction is unaffected by the noise for $\eta_0 = 0.001$. b) the reconstruction of the degree distribution for $\eta_0 = 0.003$ cannot accurately estimate the degree distribution.

5.2. Application: Bernoulli Map

Here, we study the effect of the noise problem on coupled Bernoulli maps. Consider $M = [0, 1]$, $\mathbf{x} = x$ and $\mathbf{f}_i(\mathbf{x}) = f_i(x)$ where

$$f(x) := 2x \pmod{1}. \tag{5}$$

The effect of noise on coupled Bernoulli maps for $\alpha \min k_i = 0.002$ illustrated in Figure 4. In inset a) $\eta_0 = 0.001$, the algorithm is able to reconstruct the degree distribution. In inset b) the noise has a large support $\eta_0 = 0.003$, the reconstruction is not accurate.

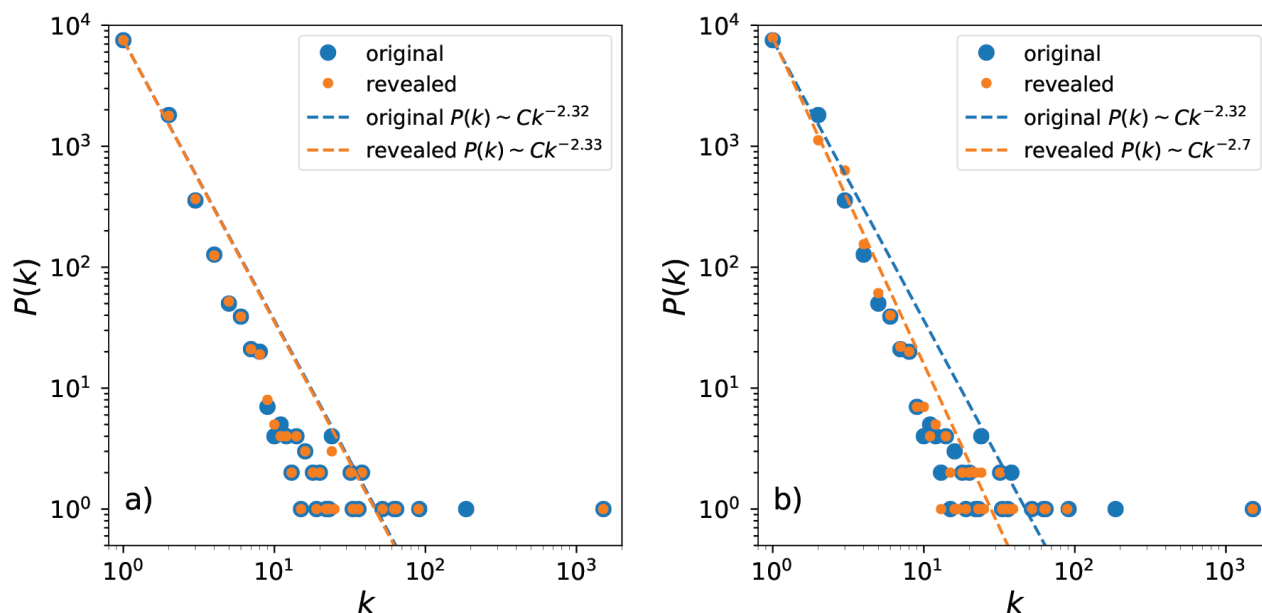


Figure 4. Performance of the reconstruction for coupled Bernoulli maps under effect of noise. Inset a) shows that the reconstruction is unaffected by the noise for $\eta_0 = 0.001$. b) the reconstruction of the degree distribution for $\eta_0 = 0.003$ cannot accurately estimate the degree distribution.

5.3. Application: Henón Map

Here, we study the effect of the noise problem on 2-dimensional coupled Henón maps,

$$f(x, y) = \begin{cases} 1 - 1.4x^2 + y \\ 0.3x \end{cases}$$

with x -coupled scheme, can be represented with the following coupling matrix \mathbf{h} ,

$$\mathbf{h} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}.$$

The effect of noise on x -coupled Henón maps for $\alpha \min k_i = 10^{-5}$ illustrated in Figure 4. In inset a) the noise is small $\eta_0 = 10^{-5}$ and the reconstruction works well. In inset b) the noise has a large support $\eta_0 = 10^{-4}$, the reconstruction fails as in previous 1-dimensional dynamical systems applications.

6. Conclusions

We have described a general procedure that allows to reconstruct degree distribution and dynamical features from time series of observations at each node of a networked system. The method, inspired by theoretical results on the ergodic properties of coupled systems, has shown very good performances when tested on large heterogeneous networks of interacting chaotic units even when there is a small size noise is involved in the application. It exploits dynamical insights, giving estimates more accurate than those obtained with generic statistical tools only.

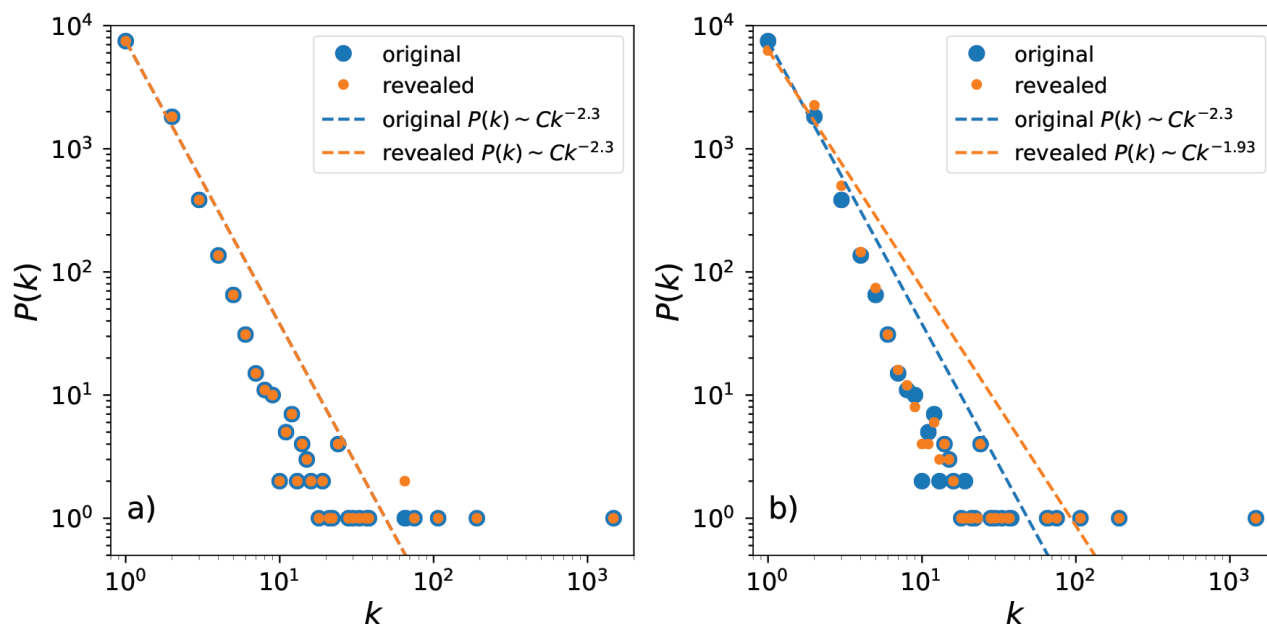


Figure 5. Performance of the reconstruction for x -coupled Henón maps under effect of noise. Henón map is a 2-dimensional map and the systems only coupled towards their x -components. Inset a) shows that the reconstruction is unaffected by the noise for $\eta_0 = 10^{-5}$. b) the reconstruction fails for $\eta_0 = 10^{-4}$ which is larger than $\alpha \min k_i$.

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